# Triangular Matrices

**Definition 1** Given an  $n \times n$  matrix A

- A is called upper triangular if all entries below the main diagonal are 0.
- A is called lower triangular if all entries above the main diagonal are 0.
- A is called diagonal if only the diagonal entries are non-zero.

If  $D$  is a diagonal matrix with diagonal entries  $d_1, d_2, \ldots d_n$ , we may write it as diag $(d_1, d_2, \ldots, d_n)$ 

### Example 2

- 1. Upper Triangular
	- a)  $\sqrt{ }$  $\overline{\phantom{a}}$ 1 3 5 7 0 9 6 4 0 0 7 8 0 0 0 1  $\setminus$  $\begin{array}{c} \hline \end{array}$ b)  $\sqrt{ }$  $\overline{\phantom{a}}$ 1 3 7 9 0 0 2 5 0 0 9 6 0 0 0 0  $\setminus$  $\begin{array}{c} \hline \end{array}$
- 2. Lower Triangular
	- a)  $\sqrt{ }$  $\overline{\phantom{a}}$ 1 0 0 0 2 3 0 0 5 9 2 0 7 6 4 8  $\setminus$  $\begin{array}{c} \hline \end{array}$

$$
\begin{pmatrix}\n1 & 0 & 0 & 0 \\
0 & 0 & 2 & 5 \\
0 & 0 & 9 & 6 \\
0 & 0 & 0 & 0\n\end{pmatrix}
$$

$$
b) \left(\begin{array}{rrrr} 1 & 0 & 0 & 0 \\ 7 & 0 & 0 & 0 \\ 5 & 0 & 0 & 0 \\ 7 & 6 & 4 & 8 \end{array}\right)
$$

3. Diagonal

a) 
$$
\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 8 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 5 \end{pmatrix} = diag(1, 3, 2, 8)
$$
  
b) 
$$
\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 5 \end{pmatrix} = diag(1, 0, 0, 5)
$$

4.  $I_n = diag(1, 1, \ldots, 1)$ , where there are n 1's. 2

### Notes:

- 1. A matrix in REF is upper triangular.
- 2. The transpose of an upper triangular matrix is lower triangular and visa versa.
- 3. The product of two Upper triangular matricies is upper triangular.
- 4. The product of two Lower triangular matricies is Lower triangular.
- 5. The product of two Diagonal matricies is Diagonal.
- 6. The transpose of a Diagonal matrix is Diagonal.

Theorem 3 A diagonal, upper or lower triangular matrix is invertable if and only if its diagonal entries are all non-zero.

 $\big)$  .

## Diagonal Matrices

**Theorem 4** Given two diagonal matricies  $D =$  $diag(d_1, \ldots, d_n)$  and  $E = diag(e_1, \ldots, e_n)$ :

- 1.  $DE = diag(d_1e_1, d_2e_2 \ldots, d_ne_n)$
- 2. For any positive integer  $k$ ,  $D^k =$  diag  $\big(d_1^k\big)$  $_{1}^{k},d_{2}^{k}\ldots,d_{n}^{k}$
- 3. D is invertable if and only if all the diagonal entries are non-zero and

$$
D^{-1} = diag\left(\frac{1}{d_1}, \ldots, \frac{1}{d_n}\right).
$$

- 4.  $D + E = diag(d_1 + e_1, d_2 + e_2, ..., d_n + e_n)$
- 5. Diagonal matrices are both upper and lower triangular. Further, any matrix which is both upper and lower triangular is diagonal.

# Symmetric Matrices

**Definition 5** An  $n \times n$  matrix A is called symmetric if it is equal to its transpose, i. e.  $A = A^T$ . It is called antisymmetric if it is equal to the negative of its transpose, i. e.  $A = -A^T$ .

Note that any diagonal matrix is symmetric.

### Example 6

1.

$$
\left(\begin{array}{rrr}\n1 & 2 & 4 \\
2 & 2 & 5 \\
4 & 5 & 3\n\end{array}\right)
$$

2. A mileage chart shows the distance between cities. Such a chaart is symmetric since the distance between city A and city B is the same as the distance from city B to City A.



**Theorem 7** Given symmetric  $n \times n$  matrices A and B then:

- 1.  $A<sup>T</sup>$  is symmetric.
- 2.  $A + B$  and  $A B$  are symmetric.
- 3. For any scalar  $k$   $kA$  is symmetric.

 $A^T$  is symmetric since  $\left(A^T\right)^T=A$ , for any matrix A.

### Example 8

1.

$$
\begin{pmatrix} 1 & 2 & 4 \ 2 & 2 & 5 \ 4 & 5 & 3 \end{pmatrix} + \begin{pmatrix} 0 & 1 & 1 \ 1 & 2 & 2 \ 1 & 2 & 3 \end{pmatrix} = \begin{pmatrix} 1+0 & 2+1 & 4+1 \ 2+1 & 2+1 & 5+1 \ 4+1 & 5+2 & 3+3 \end{pmatrix} =
$$

2.

$$
2\begin{pmatrix} 0 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{pmatrix} = \begin{pmatrix} 2 \cdot 0 & 2 \cdot 1 & 2 \cdot 1 \\ 2 \cdot 1 & 2 \cdot 2 & 2 \cdot 2 \\ 2 \cdot 1 & 2 \cdot 2 & 2 \cdot 3 \end{pmatrix} = \begin{pmatrix} 0 & 2 & 2 \\ 2 & 4 & 4 \\ 2 & 4 & 6 \end{pmatrix}
$$

Theorem 9 If A is an invertable symmetric matrix then:

1.  $A^{-1}$  is symmetric;

2.  $AA<sup>T</sup>$  and  $A<sup>T</sup>A$  are also invertable.

Note that if A is symmetric then  $AA^T = A^2$ , so  $(AA<sup>T</sup>)<sup>-1</sup> = A<sup>-2</sup> = (A<sup>-1</sup>)<sup>2</sup>$ 

Example 10

Let 
$$
A = \begin{pmatrix} 1 & 2 & 1 \\ 2 & 5 & 3 \\ 1 & 3 & 3 \end{pmatrix}
$$

1.

$$
A^{-1} = \begin{pmatrix} 6 & -3 & 1 \\ -3 & 2 & -1 \\ 1 & -1 & 1 \end{pmatrix}
$$
 (Exercise)

Which is also symmetric.

2.

$$
AAT = A2 = \begin{pmatrix} 6 & 15 & 10 \\ 15 & 38 & 26 \\ 10 & 26 & 19 \end{pmatrix}
$$

$$
(AAT)-1 = (A-1)2 = \begin{pmatrix} 6 & -3 & 1 \\ -3 & 2 & -1 \\ 1 & -1 & 1 \end{pmatrix}2 = \begin{pmatrix} 46 & -25 & 10 \\ -25 & 14 & -6 \\ 10 & -6 & 3 \end{pmatrix}
$$

$$
\begin{pmatrix} 6 & 15 & 10 \\ 15 & 38 & 26 \\ 10 & 26 & 19 \end{pmatrix} \begin{pmatrix} 46 & -25 & 10 \\ -25 & 14 & -6 \\ 10 & -6 & 3 \end{pmatrix} = I
$$

Note: Not all symmetric matrices are invertible. For example  $\sqrt{ }$  $\overline{\phantom{a}}$ 1 2 1 2 5 3 1 3 2  $\setminus$  is not invertible.  $\sqrt{ }$  $\overline{\phantom{a}}$ 1 2 1 2 5 3 1 3 2  $\setminus$  $\Big\}$  $\rightsquigarrow$  $\sqrt{ }$  $\overline{ }$ 1 2 1 0 1 1 0 1 1  $\setminus$  $\Big\}$  $R_2 \rightarrow R_2 - 2R_1$  $R_3 \to R_3 - R_1$