Lines in \mathbb{R}^3

We wish to represent lines in \mathbb{R}^3 . Note that a line may be described in two different ways:

- By specifying two points on the line.
- By specifying one point on the line and a vector parallel to it.

If we are given two points, P and Q on a line, then a vector parallel to it is \overrightarrow{PQ} .

There are three ways of representing a line algebraically.

Vector Representation of a Line

Given a point $P = (x_0, y_0, z_0)$ on the line and a vector $\mathbf{v} = (a, b, c)$ parallel to it.

An arbitrary point X = (x, y, z) on the line will be given by the vector equation:

$$\vec{OX} = \vec{OP} + t\mathbf{v}.$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix} + t \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

If we are given two points, P and Q on the line, then take $\mathbf{v} = \vec{PQ}$.

Parametric Representation of a Line

Given a point $P = (x_0, y_0, z_0)$ on the line and a vector $\mathbf{v} = (a, b, c)$ parallel to it.

An arbitrary point X = (x, y, z) on the line will be given by the system of equations:

$$x = x_0 + ta$$

$$y = y_0 + tb$$

$$z = z_0 + tc$$

If we are given two points, P and $Q = (x_1, y_1, z_1)$ on the line, then take $\mathbf{v} = \vec{PQ}$ and this becomes.

$$x = x_0 + t(x_1 - x_0)$$

 $y = y_0 + t(y_1 - y_0)$
 $z = z_0 + t(z_1 - z_0)$

Symmetric Representation of a Line

Solving for t gives the Symmetric Representation of a Line.

$$t = \frac{x - x_0}{a} = \frac{y - y_0}{b} = \frac{z - z_0}{c}$$

Note that this is only definied if a, b and c are non-zero.

1. Find the equation of the line ℓ joining P = (1,1,1) to Q = (1,0,1) in vector form.

 $\vec{PQ} = (0, -1, 0)$, so the equation os given by

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + t \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix}$$

2. Find the equation in parametric form of the line ℓ above.

$$\begin{array}{rcl}
x & = & 1 \\
y & = & 1 - t \\
z & = & 1
\end{array}$$

3. Find the equation in symmetric form of the line ℓ above.

This does not exist.

4. Does R = (1, 2, 2) lie on ℓ ?

Substituting
$$R=(1,2,2)$$
 for $X=(x,y,z)$ we get
$$1 = 1$$

$$2 = 1-t$$

$$2 = 1$$

Which has no solution, so R does not lie on the line.

5. Does S = (1, 2, 1) lie on ℓ ?

Which is true when t=-1, so this lies on the line.

6. With the parameterization above at what point will we be when t = -2

When t = -2 we will be at (1,3,1).

Planes in \mathbb{R}^3

We wish to represent planes in \mathbb{R}^3 . Note that a plane may be described in three different ways:

- By specifying three points on the plane.
- By specifying one point in the plane and two vectors parallel to it.
- By specifying one point in the plane and a vector perpendicular to it.

The third form is preferable since it needs the least information.

Let π be a plane described by a vector $\mathbf{n} = (a, b, c)$ orthogonal to it and a point $P = (x_0, y_0, z_0)$ which lies in it.

Consider a point Q = (x, y, z) on the plane π .

Since n is orthogonal to the plane $n \cdot v = 0$ for any vector v parallel to the plane.

Now $\overrightarrow{PQ} = (x - x_0, y - y_0, z - z_0)$ is in the plane.

So
$$\mathbf{n} \cdot \vec{PQ} = 0$$
, or

$$a(x-x_0) + b(y-y_0) + c(z-z_0) = 0$$

This is called the *point normal form* of the equation of a plane.

Setting
$$d = ax_0 + by_0 + cz_0 = \mathbf{n} \cdot \vec{OP}$$
, we get $ax + by + cz = d$

This is called the standard form of the equation of a plane.

Example 2

1. Find the equation of the plane π which is orthogonal to the vector n = (1, 1, 2) and through the point P = (1, 0, 1)

$$d = \mathbf{n} \cdot \vec{OP} = (1, 1, 2) \cdot (1, 0, 1) = 3$$

Equation is $\mathbf{n} \cdot \vec{OX} = d$

$$x + y + 2z = 3$$

2. Is $Q = (1, 2, 3) \in \pi$?

Put X = Q in the equation to get

$$1 + 2 + 2 \times 3 = 9 \neq 3$$

So equation is inconsistent and $Q \notin \pi$.

3. Is $Q = (3, 2, -1) \in \pi$?

Put X = Q in the equation to get

$$3+2+2\times(-1)=3$$

So equation is consistent and $Q \in \pi$.

If to vectors \mathbf{u} and \mathbf{v} parallel to the plane are given we can take solve the equations

$$\mathbf{n} \cdot \mathbf{u} = 0$$
$$\mathbf{n} \cdot \mathbf{v} = 0.$$

Generally this will result in an infinite solution set (a line through the origin). Any vector parallel to this line will work for ${\bf n}$ as all are perpendicular to the plane. The magnitude of ${\bf n}$ will affect the value of d.

Alternately we can use the cross product $\mathbf{n} = \mathbf{u} \times \mathbf{v}$. (see Section 4.3).

If a plane is defined three points P,Q and R in the plane then \vec{PQ} , \vec{PR} and \vec{QR} are all vectors parallel to the plane and the method outlined above may be used.

Find the equation of the plane π parallel to $\mathbf{u} = (1,0,1)$ and $\mathbf{v} = (2,-1,2)$, through P = (1,1,1).

Let $n = (n_1, n_2, n_3)$ be the normal vector to π .

$$\mathbf{u} \cdot \mathbf{n} = 0 \Rightarrow (1, 0, 1) \cdot (n_1, n_2, n_3) = n_1 + n_3 = 0.$$

 $\mathbf{v} \cdot \mathbf{n} = 0 \Rightarrow (2, -1, 2) \cdot (n_1, n_2, n_3) = 2n_1 - n_2 + 2n_3 = 0.$

The solution to the set of simultaneous equations

$$n_1 + n_3 = 0.$$

 $2n_1 - n_2 + 2n_3 = 0.$

are vectors of the form (t, 0, -t), for any $t \in \mathbb{R}$. We arbitrarily pick t = 1, so $\mathbf{n} = (1, 0, -1)$.

Alternately, using cross product

$$\mathbf{n} = \mathbf{u} \times \mathbf{v} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 0 & 1 \\ 2 & -1 & 2 \end{vmatrix} = \mathbf{i} - \mathbf{k}$$

Now, $d = \mathbf{n} \cdot \vec{OP} = (1, 0, -1) \cdot (1, 1, 1) = 1 - 1 = 0.$

So the equation of the plane is

$$x - z = 0$$

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Find the equation of the plane through the points P = (1, 1, 1), Q = (0, 1, 2) and R = (1, 1, 2)

 $\vec{PQ} = (-1,0,1)$ and $\vec{QR} = (1,0,0)$ are two vectors in the plane. Let $n = (n_1, n_2, n_3)$ be the normal vector to the plane.

$$\vec{PQ} \cdot \mathbf{n} = 0 \Rightarrow (-1, 0, 1) \cdot (n_1, n_2, n_3) = -n_1 + n_3 = 0.$$

 $\vec{QR} \cdot \mathbf{n} = 0 \Rightarrow (1, 0, 0) \cdot (n_1, n_2, n_3) = n_1 = 0.$

The solution to the set of simultaneous equations

$$-n_1 + n_3 = 0$$
, and $n_1 = 0$

are vectors of the form (0, t, 0), for any $t \in \mathbb{R}$. We arbitrarily pick t = 1, so n = (0, 1, 0).

Alternately, using cross product:

$$\mathbf{n} = \vec{PQ} \times \vec{QR} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -1 & 0 & 1 \\ 1 & 0 & 0 \end{vmatrix} = (0, 1, 0)$$

Now,
$$d = \mathbf{n} \cdot \vec{OP} = (0, 1, 0) \cdot (1, 1, 1) = 1$$
.

So the equation of the plane is y = 1

1. Find the point of intersection of the plane x-z=0 with the line ℓ :

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} + t \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}$$

The line can be expressed as

$$x = 2 + 2t$$
, $y = 1 - t$, $z = 1 + t$.

Intersection (x, y, z) for x, y and z which satisfy both the equation of the line and that of the plane. Substitute equation for the line into the equation for the plane and solve for t.

$$\underbrace{(2+2t)}_{x} - \underbrace{(1+t)}_{z} = 0$$
$$t+1=0$$

So the solution is t = -1.

Substituting back in the equation for the line ℓ we get the point of intersection:

$$(2-2(-1), 1-(-1), 1-1) = (0, 2, 0)$$

2. Find the point of intersection of π with the line

$$\ell \colon \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

Intersect when these are the same x, y and z. x = 1 + t, y = 1 + 2t, z = 1 + t, substitute in equation for plane and solve for t

$$\underbrace{(1+t)}_{x} - \underbrace{(1+t)}_{z} = 0$$

$$0 = 0$$

Many solutions, so the line is in the plane.

3. Find the point of intersection of π with the line

$$\ell \colon \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

Intersect when these are the same x, y and z. x=2+t, y=1+2t, z=1+t, substitute in equation for plane and solve for t

$$(2+t) - (1+t) = 0$$

1 = 0

No solution, so the line is parallel to the plane, but not in it.