

$M \times \text{Mult}^n$

Oct 7 09

$M \times \text{Mult}^n$ is NOT commutative.

i.e. $AB \neq BA$

Also can have 'Zero Divisors' i.e. M 's A, B
s.t. $AB = 0$

eg 1) a) $\overset{A}{\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}} \overset{B}{\begin{pmatrix} 0 & 2 \\ 1 & 0 \end{pmatrix}} = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$

b) $\overset{B}{\begin{pmatrix} 0 & 2 \\ 1 & 0 \end{pmatrix}} \overset{A}{\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}} = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}$

$AB \neq BA$

2) $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

3) $\overset{I_2}{\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$

I is the Identity of $M \times \text{Mult}^n$

eg $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$

Identity: $AI = IA = A$. for any $m \times n$.

Is it true that $(A+B)^2 = A^2 + 2AB + B^2$? No!

$$(A+B)^2 = (A+B)(A+B)$$

$$= A(A+B) + B(A+B) \quad (\text{Distributivity})$$

$$= A^2 + AB + BA + B^2 \quad (\text{ " })$$

But we cannot guarantee $AB = BA$.

Distributivity

$$A(B+C) = AB + AC \quad (\text{order matters})$$

Matrix Transformations

Given an $m \times n$ matrix A .

Then for every vector $\underline{x} \in \mathbb{R}^n$ we can define a vector $\underline{y} \in \mathbb{R}^m$ by $\underline{y} = A\underline{x}$

We call this transformation the transformation associated with A & write $T_A(\underline{x}) = A\underline{x}$

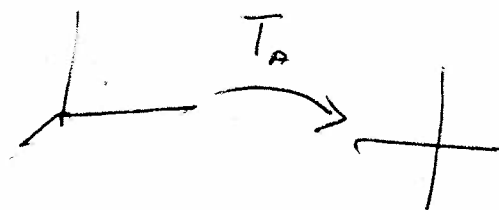
eg 1) $A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix}$

$\underline{y} = A\underline{x}$ $\underline{y} \in \mathbb{R}^2, \underline{x} \in \mathbb{R}^3$

~~$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$~~ $\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$

$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} x_1 + x_2 \\ x_2 + x_3 \end{pmatrix}$

or $y_1 = x_1 + x_2$
 $y_2 = x_2 + x_3$



eg $T_A(1, 1, 0) = (2, 2)$

$T_A(1, 1, 0) = (2, 1)$

total We write $T_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$

2) $A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}$ $T_A: \mathbb{R}^2 \rightarrow \mathbb{R}^3$

$\begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \\ 0 \end{pmatrix}$



$y_1 = x_1$
 $y_2 = x_2$
 $y_3 = 0$

Maps \mathbb{R}^2 onto the x, y plane ($z=0$) of \mathbb{R}^3

If we fix $\underline{b} \in \mathbb{R}^m$ ask what values of $\underline{x} \in \mathbb{R}^n$ map to \underline{b} via T_A

i.e. For what values of $\underline{x} \in \mathbb{R}^n$ is $A\underline{x} = \underline{b}$?

eg 1) Find $\underline{x} \in \mathbb{R}^3$ s.t. $A\underline{x} = \underline{b}$ where $\underline{b} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} x_1 + x_2 \\ x_2 + x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

i.e. $x_1 + x_2 = 1$
 $x_2 + x_3 = 1$

This question actually asks for the solⁿ to a system of eq^s.

In general The eqⁿ $A\underline{x} = \underline{b}$ is actually a short form for an $m \times n$ system of eq^s with coeff. $m \times A$.

\uparrow \uparrow
 m eq^s n unknowns

$M \times M$ Matⁿ

Given 2 $m \times m$'s A & B s.t. AB is defined.

Consider $\underline{y} = AB\underline{x}$ ($\underline{y} = T_{AB}(\underline{x})$)

Let $\underline{z} = B\underline{x}$ ($\underline{z} = T_B(\underline{x})$)

Then $\underline{y} = A\underline{z}$ ($\underline{y} = T_A(\underline{z}) = T_A(T_B(\underline{x}))$)

i.e. $T_{AB}(\underline{x}) = T_A(T_B(\underline{x}))$

So Matrix Multⁿ corresponds to composⁿ of maps
 $T_{AB}(\underline{x}) = T_A(T_B(\underline{x})) = (T_A \circ T_B)(\underline{x})$

$$AB\underline{x} = A(B\underline{x})$$

Linear Eqⁿ's Revisited

Suppose we have an $m \times n$ matrix A & a specific $\underline{b} \in \mathbb{R}^m$

$\underline{b} = (b_1, b_2, \dots, b_m)$ Consider the eqⁿ's $A\underline{x} = \underline{b}$

Where $\underline{x} = (x_1, \dots, x_n)$ are unknowns.

Notatⁿ A Solutⁿ to $A\underline{x} = \underline{b}$ is the set of all $\underline{x} \in \mathbb{R}^n$
s.t. $A\underline{x} = \underline{b}$

The kernel is the set of all $\underline{x} \in \mathbb{R}^n$ s.t. $A\underline{x} = \underline{0}$

i.e. The solⁿ to the Homogeneous system $A\underline{x} = \underline{0}$

The kernel is the set of points mapped to $\underline{0} \in \mathbb{R}^m$ by
the transformⁿ $T_A(\underline{x})$

Algebra of $n \times n$'s

Cancellatⁿ law work for matrix additⁿ & scalar multⁿ. But NOT $n \times n$ multⁿ.

$$1) A+B=C \Rightarrow A=C-B$$

$$2) kA=B \Rightarrow A=\frac{1}{k}B \quad (k \neq 0)$$

So we can do a certain amount of Algebra
eg Find the $n \times n$ X s.t.

$$\text{Where } 2X + A = B$$
$$A = \begin{pmatrix} -1 & 2 & 1 \\ 0 & 1 & -3 \\ 2 & 0 & 0 \end{pmatrix} \quad B = \begin{pmatrix} 1 & 4 & 1 \\ 6 & -1 & 3 \\ -2 & 2 & 2 \end{pmatrix}$$

$$2X + \begin{pmatrix} -1 & 2 & 1 \\ 0 & 1 & -3 \\ 2 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 4 & 1 \\ 6 & -1 & 3 \\ -2 & 2 & 2 \end{pmatrix}$$

$$2X + A = B \Rightarrow 2X = B - A \Rightarrow X = \frac{1}{2}(B - A)$$

$$B - A = \begin{pmatrix} 1 & 4 & 1 \\ 6 & -1 & 3 \\ -2 & 2 & 2 \end{pmatrix} - \begin{pmatrix} -1 & 2 & 1 \\ 0 & 1 & -3 \\ 2 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 2 & 2 & 0 \\ 6 & -2 & 6 \\ -4 & 2 & 2 \end{pmatrix}$$

$$\frac{1}{2}(B - A) = \begin{pmatrix} 1 & 1 & 0 \\ 3 & -1 & 3 \\ -2 & 1 & 1 \end{pmatrix}$$

Problem Matrix 'Division' is not well defined

We can define the inverse of a square $n \times n$ A , A^{-1} to be a $n \times n$ s.t. $AA^{-1} = I = A^{-1}A$.

But Not all $n \times n$'s have an inverse.

eg $\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$ has no inverse

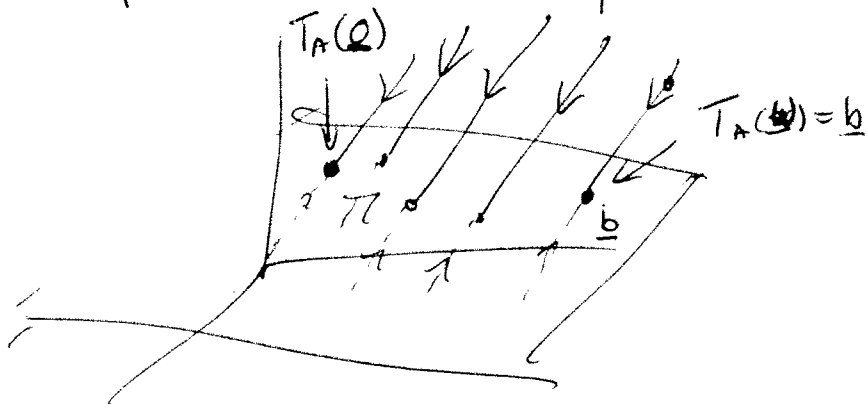
i.e. There is no matrix B s.t. $\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} B = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = I$

$$B = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad \Rightarrow \quad \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a+c & b+d \\ a+c & b+d \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{aligned} a+c &= 1 \\ a+c &= 0 \end{aligned} \quad \text{inconsistent.}$$

If a $n \times n$ has an inverse we call it invertible
otherwise it is non invertible.

Suppose a $n \times n$ maps \mathbb{R}^3 to a plane



Recall $A\underline{h} = \underline{0}$ & $A\underline{w} = \underline{b}$

then $A(\underline{h} + \underline{w}) = \underline{b}$

$\underline{h} \in \ker(A)$ & $A\underline{w} = \underline{b}$
then $\underline{w} + \underline{h}$ is a solⁿ of $A\underline{x} = \underline{b}$

If \underline{h} is a solⁿ to the homogeneous system $A\underline{x} = \underline{0}$ & \underline{w} is a solⁿ to $A\underline{x} = \underline{b}$ then $\underline{w} + \underline{h}$ is a solⁿ to $A\underline{x} = \underline{b}$