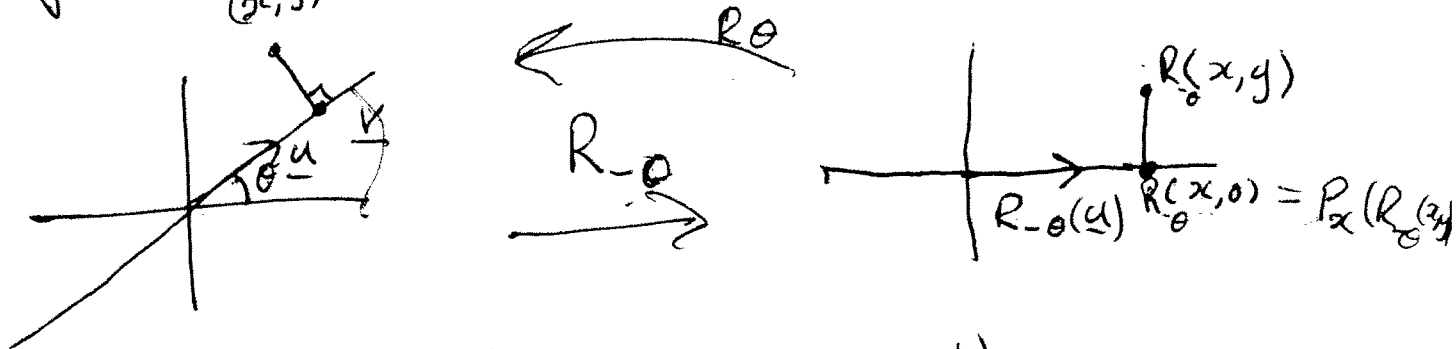
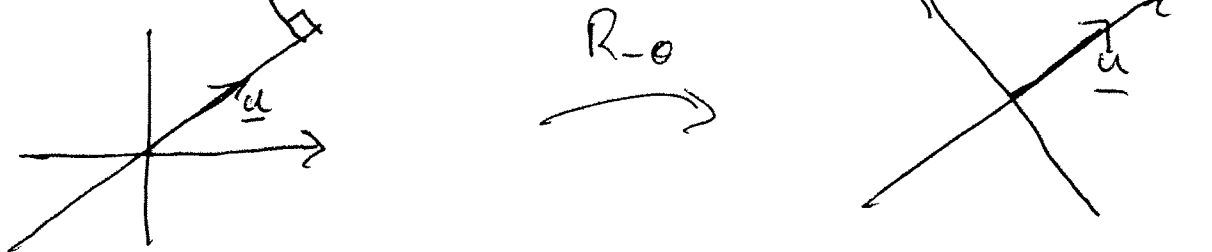


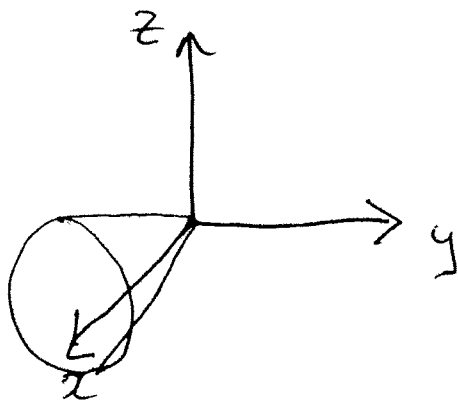
Projectⁿ onto x -axis in \mathbb{R}^2



$$v = R_\theta(P_x(R_{-\theta}(x, y)))$$

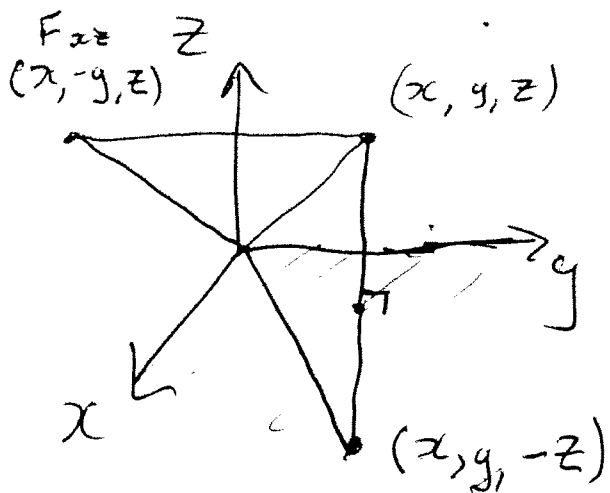


Rotatⁿ about x -axis in \mathbb{R}^3



x coord. doesn't change
rotatⁿ in the yz -plane.

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & R_\theta \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \\ - \\ - \end{pmatrix}$$



$$F_{xy}(1, 0, 0) = (1, 0, 0)$$

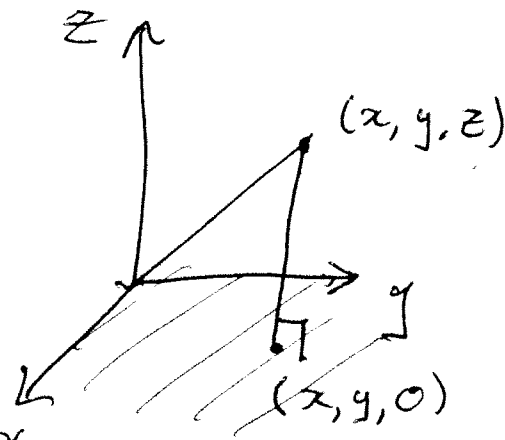
$$F_{xy}(0, 1, 0) = (0, 1, 0)$$

$$F_{xy}(0, 0, 1) = (0, 0, -1)$$

$$[F_{xy}] = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

Projectⁿs in \mathbb{R}^3

(2)



$$\begin{aligned}P_{xy}(1, 0, 0) &= (1, 0, 0) \\P_{xy}(0, 1, 0) &= (0, 1, 0) \\P_{xy}(0, 0, 1) &= (0, 0, 0)\end{aligned}$$

$$[P_{xy}] = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Composition of Maps

We know that composition of ^{matrix} maps is just matrix multiⁿ. i.e. $T_A(T_B(x)) = T_{AB}(x)$

eg) Find the standard mx for the transformⁿ in \mathbb{R}^2 given by a reflectⁿ about the x-axis, followed by a rotatⁿ by 60° ~~counter~~ clockwise.

$$F_x = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$R_\theta = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \quad \theta = 60^\circ = \frac{\pi}{3}$$

$$R_{\frac{\pi}{3}} = \begin{pmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix}$$

$$= \frac{1}{2} \begin{pmatrix} 1 & -\sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$$

$$\begin{aligned}T_{AB} &= R_\theta(F_x(x)) \quad A = [R_\theta][F_x] - \\ &= \frac{1}{2} \begin{pmatrix} 1 & -\sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 & \sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix}\end{aligned}$$

2) Find the ~~standard~~ ^{std} mx for the $\textcircled{3}$ transformⁿ in \mathbb{R}^3 obtained by a counterclockwise rotatⁿ about the y -axis of 60° followed by a dilatⁿ by a factor 2.

$$[R_y] = \begin{pmatrix} \cos\theta & 0 & \sin\theta \\ 0 & 1 & 0 \\ -\sin\theta & 0 & \cos\theta \end{pmatrix} \quad [D_2] = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$A = [D_2][R_{\frac{\pi}{3}}] = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & 0 & +\frac{\sqrt{3}}{2} \\ 0 & 1 & 0 \\ -\frac{\sqrt{3}}{2} & 0 & \frac{1}{2} \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & +\sqrt{3} \\ 0 & 2 & 0 \\ -\sqrt{3} & 0 & 1 \end{pmatrix}$$

3) Find the standard mx for the mapping in \mathbb{R}^3 obtained by a reflectⁿ about the yz -plane, followed by an orthogonal projectⁿ onto the xz -plane.

$$[R_{yz}] = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad [P_{xz}] = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$[P_{xz}][R_{yz}] = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Subspaces Review

- For all
- 1) $\forall \underline{x}, \underline{y} \in U \quad \underline{x} + \underline{y} \in U$
 - 2) $\forall \underline{x} \in U, c \in \mathbb{R} \quad c\underline{x} \in U$

eg 1) $U = \{ (x, x^2) \mid x \in \mathbb{R} \}$

↑ ↑ ↑ ↓
the set form such that condition

[Not a Subspace]

[Look for a pair of vectors where some rule fails]

$$(1, 1) + (2, 4) = (3, 5) \quad 5 \neq 3^2$$

So $(1, 1) \in U, (2, 4) \in U$ but $(1, 1) + (2, 4) \notin U$.

- So Rule 1 does not hold for every pair.

Alternately could have shown Rule 2 broken.

$$2(1, 1) = (2, 2) \notin U \quad (2^2 \neq 2)$$

2) $U = \{ \underline{x} + \underline{a} \in \mathbb{R}^2 \mid \underline{a} = (1, 1), \underline{x} \in \mathbb{R}^2 \}$

$$\{ (x, x^y) \in \mathbb{R}^2 \mid x^y \in \mathbb{R} \}$$

$(0, 0) \notin U$ so not a subspace, $x, y > 0$

3) $U = \{ \underline{x} \in \mathbb{R}^3 \mid ax + by + cz = 0, a, b, c \text{ fixed} \}$

The solution to any homogeneous system of (the plane $ax + by + cz = 0$)
 eq^n s is always a subspace through.

$ax + by + cz = 0$ is a homogeneous 1^{st} eqⁿ in 3 unknowns.

$$U = \{(x, y, z) \in \mathbb{R}^3 \mid ax + by + cz = 0\}$$

→ Let $\underline{u}, \underline{v} \in U$.

→ So $au_1 + bu_2 + cu_3 = 0$ & $av_1 + bv_2 + cv_3 = 0$

[- Defining Property of vectors in U.]

[Must Show $\underline{u} + \underline{v}$ has defining property of U so $\underline{u} + \underline{v} \in U$]

Consider $\underline{u} + \underline{v} = (u_1 + v_1, u_2 + v_2, u_3 + v_3)$

Consider $a(u_1 + v_1) + b(u_2 + v_2) + c(u_3 + v_3)$ [Have to show this is 0]

$$= au_1 + bu_2 + cu_3 + av_1 + bv_2 + cv_3$$

$$= 0 + 0 = 0$$

So $\underline{u} + \underline{v} \in U$

Let $\underline{u} \in U$ & $d \in \mathbb{R}$ so $au_1 + bu_2 + cu_3 = 0$

$$d\underline{u} = (du_1, du_2, du_3)$$

Consider $a(du_1) + b(du_2) + c(du_3)$

$$= 0$$

So $d\underline{u} \in U$.

4) Show $\{(x, y, z) \in \mathbb{R}^3 \mid ax + by + cz = 1\}$ is NOT a subspace.

$$a \cdot 0 + b \cdot 0 + c \cdot 0 = 0 \neq 1$$

So $(0, 0, 0) \notin U \Rightarrow$ Not a s.s.

Lin indep $\underline{u}_i \in \mathbb{R}^n$
 $a_1 \underline{u}_1 + a_2 \underline{u}_2 + \dots + a_k \underline{u}_k = \underline{0}$
 has only the trivial solⁿ $a_1 = a_2 = \dots = a_k = 0$

Method 1 ($k \neq n$) Form the matrix whose
 cols are the \underline{u}_i $A_u = (\underline{u}_1 | \underline{u}_2 | \dots | \underline{u}_k)$

$$A_u \underline{a} = \underline{0}$$

$$\underline{u}_1 = (1, 0, 1) \quad \underline{u}_2 = (1, 1, 0) \quad k=2, n=3$$

$$a_1 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + a_2 \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\left(\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{array} \right) R_3 \rightarrow R_3 - R_1$$

only solⁿ $a_1 = a_2 = 0$

$$\left(\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 0 \end{array} \right) R_3 \rightarrow R_3 + R_2$$

So lin indep

$$\left(\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

Method 2 only works when $k=n$

Now A_u is square

Homogeneous system has ^{non-trivial} solⁿ iff $\det(A_u) \neq 0$

eg $\underline{u}_1 = (1, 0, 1) \quad \underline{u}_2 = (1, 1, 0) \quad \underline{u}_3 = (2, 1, 1)$

$$|A_u| = \begin{vmatrix} 1 & 1 & 2 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{vmatrix} = \begin{vmatrix} 1 & 1 \\ 0 & 1 \end{vmatrix} - \begin{vmatrix} 0 & 1 \\ 1 & 1 \end{vmatrix} + 2 \begin{vmatrix} 0 & 1 \\ 1 & 0 \end{vmatrix}$$

$$= 1 + 1 - 2 = 0$$

So lin. dep. In fact $\underline{u}_1 + \underline{u}_2 - \underline{u}_3 = \underline{0}$

$$\left(\begin{array}{ccc|c} 1 & 1 & 2 & 0 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \end{array} \right) R_3 \rightarrow R_3 - R_1$$

$$\left(\begin{array}{ccc|c} 1 & 1 & 2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & -1 & -1 & 0 \end{array} \right) R_3 \rightarrow R_3 + R_2$$

$$\left(\begin{array}{ccc|c} 1 & 1 & 2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

∞ many solⁿs.

So Dependent.

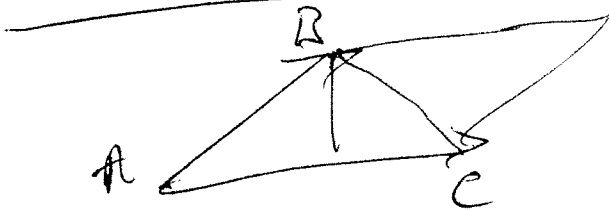
Let $t \in \mathbb{R}$, $z = t$, $y = -t$, $x = t - 2t = -t$
 $t(-1, -1, 1)$

$$t\underline{u}_1 + t\underline{u}_2 - t\underline{u}_3 = \underline{0} \quad \text{for any } t \in \mathbb{R}.$$

$$\left(\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & a \\ 1 & 0 & 1 & 0 \end{array} \right)$$

$$\left(\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & a \\ 0 & -1 & 0 & 0 \end{array} \right)$$

$$\left(\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & & & \end{array} \right)$$



$$\frac{\frac{1}{2} \|\vec{AB} \times \vec{AC}\|}{\frac{1}{2} \text{base} \times \text{height}, \vec{AC}}$$