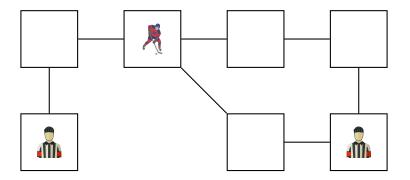
Surrounding an Active Robber

Todd Mullen Joint Work with Nancy Clarke and Stephen Finbow

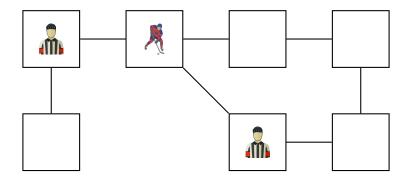
University of Prince Edward Island

GRASCan 2022 August 4, 2022

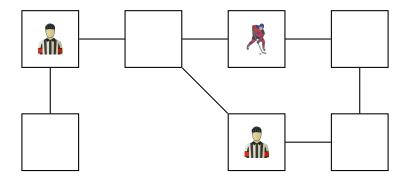
Todd Mullen Joint Work with Nancy Clarke and Stephen Finbow Surrounding an Active Robber



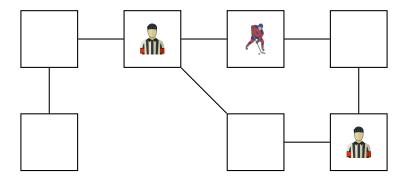
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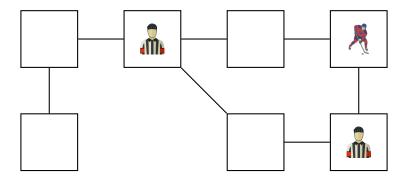
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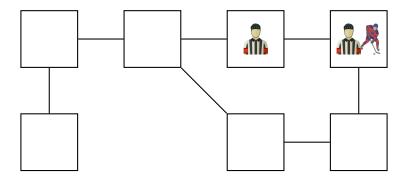
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Todd Mullen Joint Work with Nancy Clarke and Stephen Finbow Surrounding an Active Robber



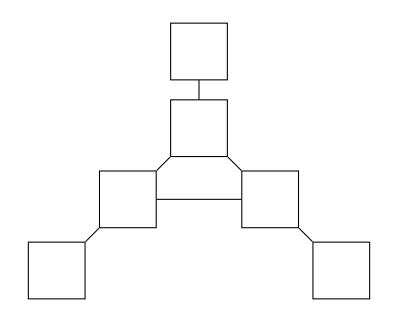
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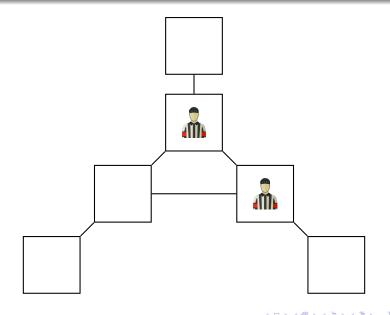
• A Cop landing on the Robber's vertex does not end the game, but rather simply compels him to move on his next turn

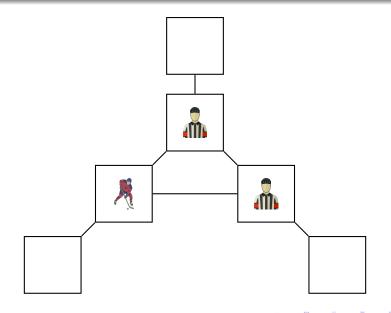
- A Cop landing on the Robber's vertex does not end the game, but rather simply compels him to move on his next turn
- The Robber may never move to any Cop's vertex

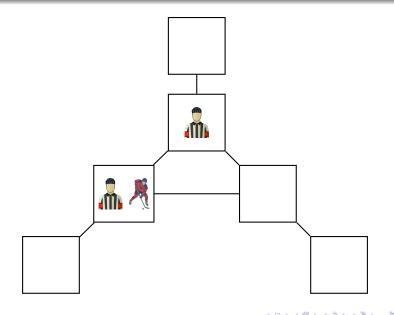
- A Cop landing on the Robber's vertex does not end the game, but rather simply compels him to move on his next turn
- The Robber may never move to any Cop's vertex
- The Robber only loses when every one of his adjacent vertices contains a Cop (he is surrounded)

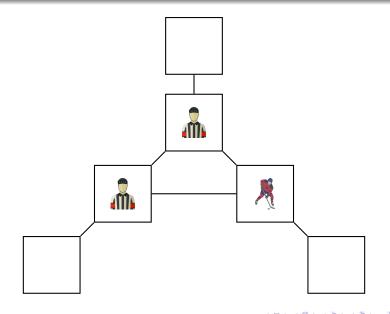


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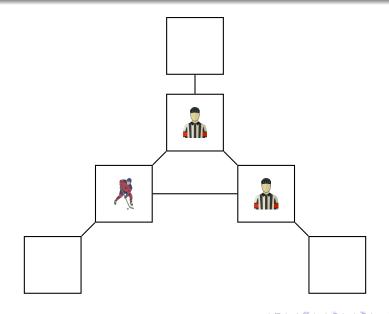
Todd Mullen Joint Work with Nancy Clarke and Stephen Finbow Surrounding an Active Robber

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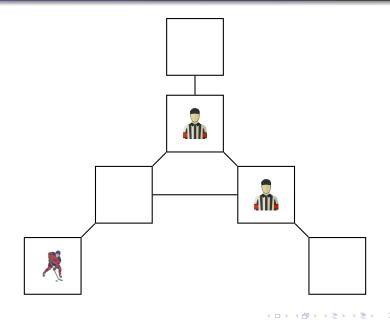
• Robber does not lose by sharing a vertex with Cop.

- Robber does not lose by sharing a vertex with Cop.
- Robber must move every turn.

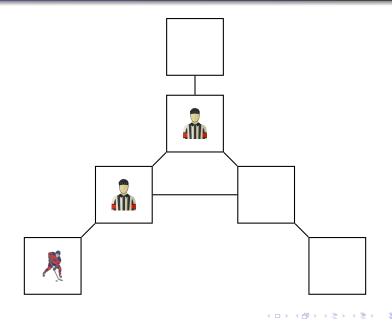
Active Surrounding Cops and Robber



Active Surrounding Cops and Robber



Active Surrounding Cops and Robber



- Robber does not lose by sharing a vertex with Cop.
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Cheating Robot $(c_{cr}(G))$ Huggan and Nowakowski, Cops and an insightful robber, *Discrete Appl. Math.*, **295** (2021), 112-119.

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- Robber must move every turn.

Cheating Robot $(c_{cr}(G))$

Huggan and Nowakowski, Cops and an insightful robber, *Discrete Appl. Math.*, **295** (2021), 112-119.

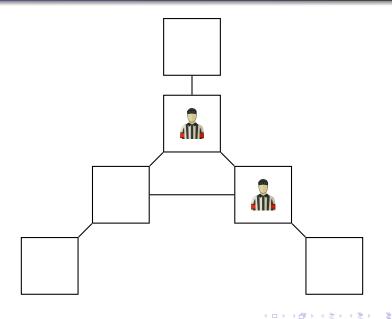
• Cops and Robber move at the same time, but the Robber knows what moves the Cops will make

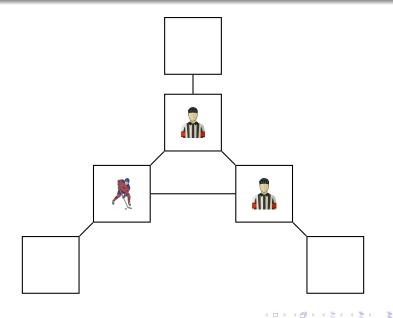
- Robber does not lose by sharing a vertex with Cop.
- Robber must move every turn.

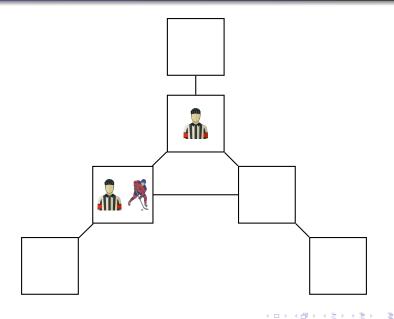
Cheating Robot $(c_{cr}(G))$

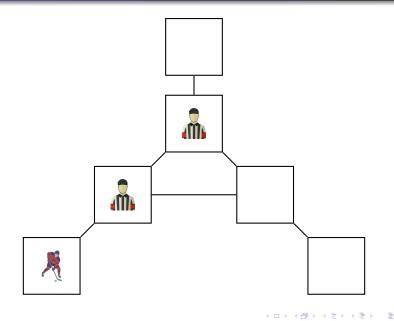
Huggan and Nowakowski, Cops and an insightful robber, *Discrete Appl. Math.*, **295** (2021), 112-119.

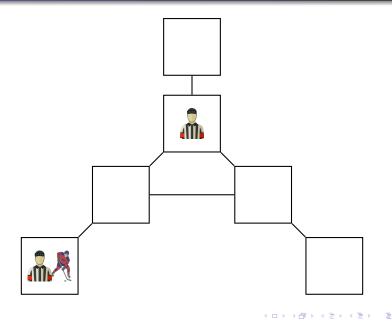
- Cops and Robber move at the same time, but the Robber knows what moves the Cops will make
- Robber loses when he shares a vertex with a Cop or moves along the same edge as a Cop in the same turn











Bounds

Todd Mullen Joint Work with Nancy Clarke and Stephen Finbow Surrounding an Active Robber

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• $c_{cr}(G) \ge c(G)$

Todd Mullen Joint Work with Nancy Clarke and Stephen Finbow Surrounding an Active Robber

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•
$$c_{cr}(G) \leq \sigma(G)$$

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$$2c_{cr}(G) \ge \sigma_a(G)$$

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- $c_{cr}(G) \ge c(G)$
- $\sigma_a(G) \leq \sigma(G) \leq \sigma_a(G) + 1$
- $c_{cr}(G) \leq \sigma(G)$
- $2c_{cr}(G) \ge \sigma_a(G)$
- For all graphs G with minimum degree $\delta \ge 3$, if G has girth $g \ge 9$, then $\sigma_a(G) \ge 5$.

Is the active number always equal to the cheating number?

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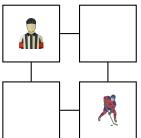
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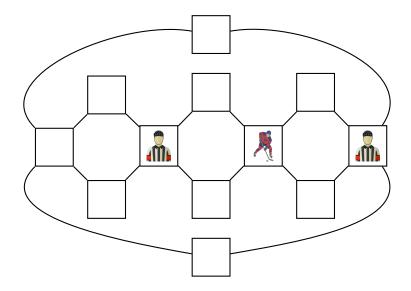
Building a Counterexample

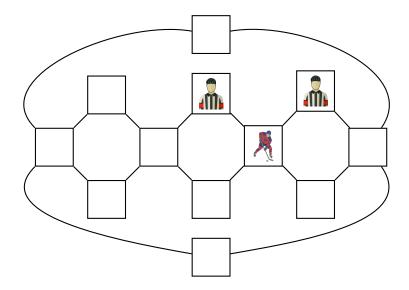
Todd Mullen Joint Work with Nancy Clarke and Stephen Finbow Surrounding an Active Robber

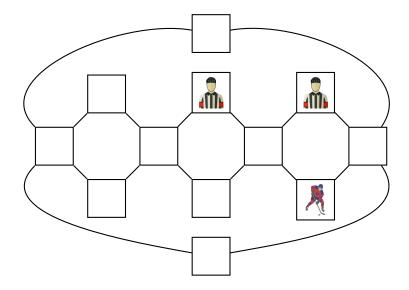
• 4-cycles appear to be important.

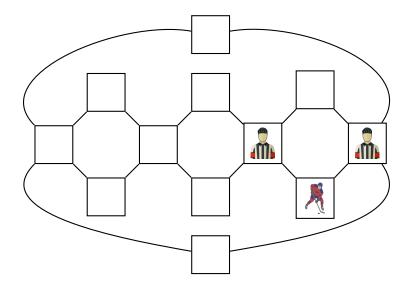
• 4-cycles appear to be important.

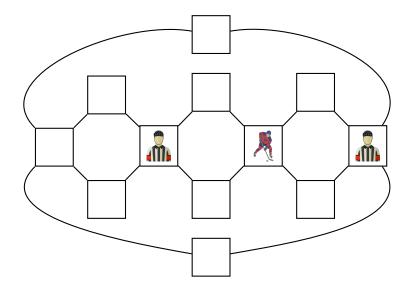




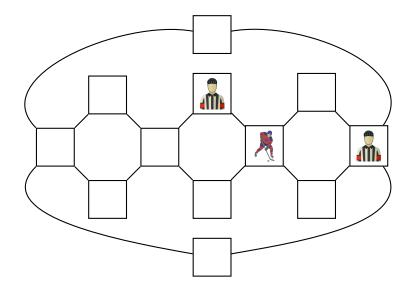




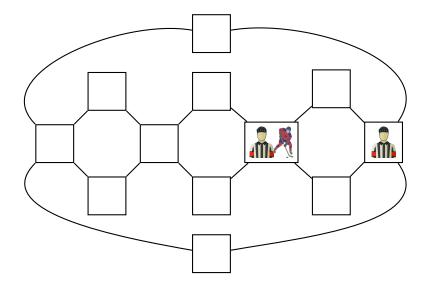




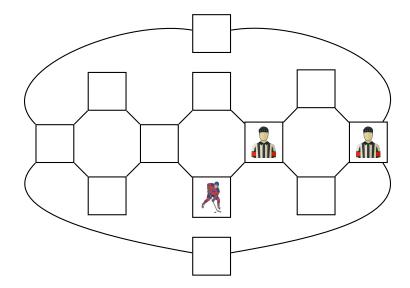
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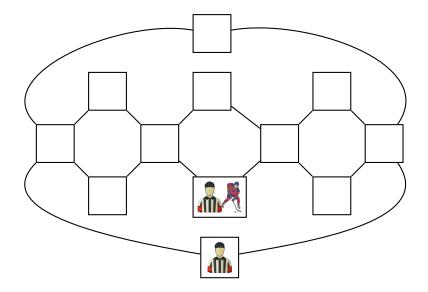
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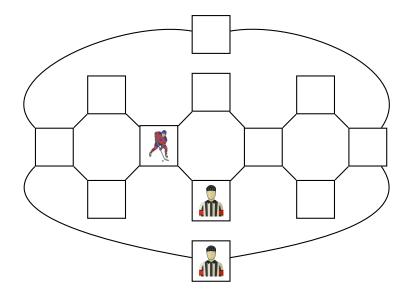
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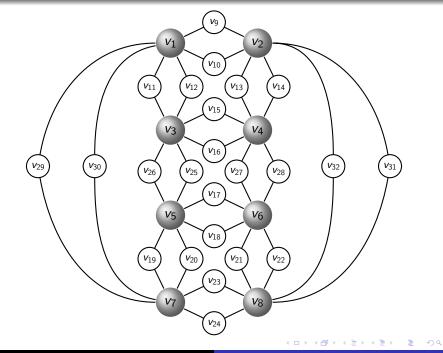
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The subdivision graph S(G) of a graph G is the graph formed by subdividing every edge in G once. We define the *double subdivision graph*, DS(G), as the graph formed by the following two steps:

- Duplicate every edge in G (call this multi-graph G')
- Subdivide every edge in G'



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